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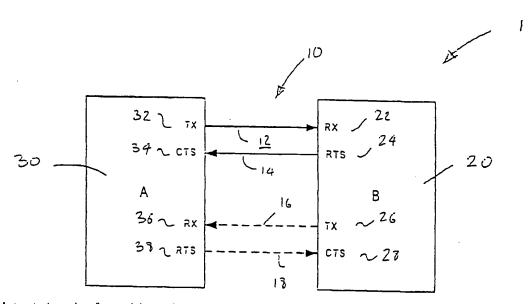
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(54) Title: ASYNCHRONOUS SERIAL DATA INTERFACE



(57) Abstract: A receiver for receiving packet data from a transmitter, the transmitter and the method of controlling transmission. The receiver may comprise first detection means for detecting that its memory has enough space to store a data packet and flow control signal means for providing a flow control signal, preferably a first flow control signal, to the transmitter in response to said first detection means. The receiver may comprise second detection means for detecting when a first portion of a packet has been received from the transmitter and flow control signal means for providing a second flow control signal to the transmitter in response to said second detection means. The transmitter may comprise third detection means for detecting the second flow control signal sent by the receiver and packetwise transmission means arranged, responsive to the third detection means, to complete transmission of a partially transmitted packet and then to stop transmission of further packets.

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Asynchronous Serial Data Interface

This invention relates to a serial communication system with data flow on a cable. e.g. a Universal Asynchronous Receiver / Transmitter (UART). The data is packet data.

A UART has a data connector connecting a transmitter to a receiver. The data sent from the transmitter to the receiver may be packet data. A packet is made up of multiple bytes of data. When the transmitter is sending packets asynchronously to the receiver it is important for the receiver to know where one packet ends and the next packet begins.

It is known for the receiver to count received bits/bytes from the start of communication. The first data bytes the receiver receives then must be the start of a packet. The receiver knows length information about the packet, and from this information the receiver can calculate when the end of the packet is received. Consequently, the next bytes it receives must be the start of the next packet. Thus the transmitter and receiver remain synchronised at the packet level.

Now, if an unknown number of bytes is lost because they don't fit in the receive buffer any more ("buffer overflow") the receiver loses packet synchronisation, i.e. the knowledge about when the next packet begins. In order to prevent buffer overflow in the receiver a flow control mechanism is needed.

A UART has a data connector connecting a Transmitter to a Receiver and a control connector connecting the transmitter and receiver. Data in bit serial format is transported from the transmitter to the receiver via the data connector. The control connector carries a control signal RTS/CTS which implements flow control from receiver to transmitter by indicating "flow on" (RTS/CTS active) or "flow off" (RTS/CTS inactive). Flow control prevents too much data being sent by the transmitter and causing overflow of the receiver

Bytes can get lost if the software in the receiver and the transmitter does not react fast enough to prevent buffer overflow. In this case packet synchronisation on the interface is lost.

To overcome the problem of loss of synchronisation when software flow control is used, a "packet delimiting" mechanism has been used. Packets are preceded/followed by a certain pattern as a packet delimiter. However, there are certain problems because the same delimiting pattern may occur within the packet that shall be transmitted. This problem has been solved, for example, by the SLIP software protocol in which any occurrence of the delimiter in the data stream have to be replaced by "Escape sequences". However, the software implementation of such a protocol is computationally intensive.

Therefore when there is no hardware support for flow control, bytes can get lost if the software does not react fast enough to prevent buffer overflow and either a complex and computationally intensive software protocol is used to delimit the packets or packet synchronisation on the interface is lost.

It would be desirable to provide an alternative flow control mechanism which provides packet synchronisation.

It would be desirable to provide the mechanism in software with a very low processing cost.

It would be desirable to provide the mechanism without altering the content or size of the packets.

According to a first aspect of the present invention there is provided a receiver, for receiving packet data from a transmitter, comprising: an output for issuing flow control signals to the transmitter; an input for receiving data from the transmitter; a memory for storing data received from the transmitter; first detection means for detecting that the memory has enough space to store a data packet; and flow control signal means for providing a flow control signal

The flow control means provides a second flow control signal, stopping the transmitter from transmitting the next data packet, in response to the second detection means.

The receiver may additionally comprise: first detection means for detecting that the memory has enough space to store the next packet to be received, wherein the flow control signal means provides a first flow control signal in dependence upon the first detection means. The first flow control signal enables the transmitter to transmit the next packet.

According to this aspect of the present invention there is provided a method of controlling packet data transmission from a transmitter to a receiver by sending flow control signals from the receiver to the transmitter, comprising the steps of: sending a flow control signal for disabling further transmission of data packets, while a current packet is being received and in time to allow the transmitter software to respond thereto and to stop transmission before the beginning of the next packet is transmitted.

The flow control signal is preferably a voltage transition. The first and second signals are preferably complimentary signals. The first flow control signal preferably corresponds to a positive transition in RTS/CTS. The second flow control signal preferably corresponds to a negative transition in RTS/CTS.

The packet may comprise a header and a payload. It may be of variable size. The header preferably identifies the packet size to the receiver. The receiver may have means for determining the start of a packet and means for counting the bits/bytes received from the start of a packet. The receiver may have means for reading the packet length of the current packet from a received header.

According to the preferred embodiment, the first detection means may detect that the memory has enough space to store the next packet to be received, for each packet. The receiver may have means for reserving sufficient

Compared to the hardware protocol the invention prevents the hardware overhead. A significant advantage of embodiments of the present invention is that they can still be implemented when the hardware is fixed and cannot be changed.

A current mobile phone may use an integrated circuit without hardware flow control on its I/O interface. As the integrated circuit is already being produced it is no longer possible to change the circuit and add hardware flow control. It would be particularly advantageous to be able to add a module to an existing mobile phone to enhance the phone's functions. One such module could be a Bluetooth transceiver. For such a module, it is imperative that packets of data can be transferred between module and phone without loosing packet synchronisation. Such transfer can be provided according to the present invention.

A "general purpose IO (input/output)" of the phone can be set by software (when being an output) or cause an interrupt on a level change (when being an input). One IO may be used for RTS/CTS of reception, and one IO may be used for RTS/CTS of transmission.

Embodiments of the invention therefore also particularly relate to computer program products which may be added to a device to program the general purpose I/O and allow it to function as a transmitter and/or a receiver according to the invention.

According to a further aspect of the present invention there is provided a computer program product which provides in a receiver having an input for receiving data, a memory for storing data and an output: first detection means for detecting that the memory has enough space to store a data packet and flow control signal means for providing a flow control signal at the output in response to the first detection means.

According to another aspect of the present invention there is provided a

Figure 1 shows a system with a serial communication interface;

Figure 2 shows the packet structure; and

Figure 3 shows the signal timing of the protocol.

Figure 1 illustrates a serial communication system 1 with packet data flow on a single cable, possibly in each direction.

The system 1 has a Transmitter 30 and a Receiver 20 interconnected via interface 10. The interface has a data connector 12 connecting pin 32 of the transmitter to pin 22 of the receiver and has a control connector 14 connecting pin 24 of the receiver to pin 34 of the transmitter. Data in bit serial format is transported from the transmitter to the receiver via pin 32, the data connector 12 and pin 22. The control connector 14 carries a control signal RTS/CTS asserted on pin 24 of the receiver. The control signal implements flow control from receiver to transmitter by indicating "flow on" (RTS/CTS active) or "flow off" (RTS/CTS inactive). Thus data transmission from left to right with flow control can be achieved.

If data transmission from right to left is required, device 20 can acts as transmitter and device 30 can act as receiver. Data in bit serial format is transported from the transmitter 20 to the receiver 30 via pin 26 the data connector 16 and then pin 36. A control connector 18 carries a control signal RTS/CTS asserted on pin 38 of the receiver to pin 28 of transmitter.

The production of RTS/CTS on the data connector by the receiver and the response to RTS/CTS in the transmitter are controlled by software.

The basic usage of RTS/CTS is conventional in that it means "flow on/off" when set active/inactive. The production of and response to RTS/CTS is not conventional and is controlled by a programmed processors in the receiver and transmitter.

It is also important for the present invention, as will become more clear presently, for the transmitter to be aware of packet boundaries. The transmitter gets the packets from some higher software layer. This other software layer could frame the packet or put it in a certain location so that the transmitter always knows the packet boundaries (or at least the packet start). Alternatively the packet length could be looked up in the packet, in the same way that the receiver does it and the transmitted bytes counted.

Preferred Embodiment

The flow control between transmitter and receiver is handled packet wise. The detection of the rising edge of RTS/CTS allows the transmission of only one packet. The receiver de-asserts the RTS/CTS inactive once the packet header has been received. The transmitter is not allowed to transmit the next packet until detection of another rising edge of the RTS/CTS signal. The flow control handling is illustrated in Figure 3. When the RTS/CTS goes inactive the transmitter completes transmission of the current packet. When RTS/CTS goes from inactive to active this signals the transmission of the next single packet.

Referring to Fig. 3, RTS/CTS goes active at time T_1 . There is a latency t_1 for detection of the rising edge at the transmitter. The transmitter detects the rising edge at T_2 . The transmitter takes t_2 to transmit the packet header and starts transmitting the rest of the packet at T_3 which takes t_3 . The transmitter finishes transmitting the packet at T_5 . There is a latency t_4 in the receiver detecting the transmitted packet header and this detection occurs at $T_4 = T_3 + t_4$, and RTS/CTS goes inactive.

The receiver puts RTS/CTS inactive after each and every packet header is received. The receiver then checks there is enough room for the next packet before putting RTS/CTS from inactive to active. The transmitter sends a single packet then waits for the RTS/CTS inactive-active transition (rising edge) before transmitting the next single packet. Thus transmission is packet wise and enabled by the CTS/RTS inactive-active transition.

- f) start transmission of a single packet in response to detection of RTS/CTS active.
- g) go to a).

The determination could be done as follows. The transmitter has a counter which maintains a count C of bits/bytes transmitted. The counter is reset to zero at the start of a packet. The transmitter continues to transmit until C = N'-1, then stops transmitting.

Step b) is optional. Each falling edge (Active to Inactive) followed by a rising edge (Inactive to Active) of RTS/CTS may indicate that a packet should be transmitted or alternatively, each rising edge (Inactive to Active) of RTS/CTS may indicate that a packet should be transmitted. The CTS input of the transmitter causes an interrupt on each level change or, alternatively, only on the rising edge.

For an already started packet the RTS/CTS level change won't cause any effect (transmission is continued whatever happens as the receiver has indicated by a "flow on" level that it can receive the max. packet size).

Embodiment 2

When the RTS/CTS goes low the transmitter completes transmission of the current packet. When RTS/CTS goes from inactive to active this signals the transmission of the next packet.

The receiver monitors the remaining memory and an alert is created when the remaining memory falls below some threshold and is reset when the available memory rises above the threshold. The receiver puts RTS/CTS inactive only when there is an alert AND after a packet header has been received. That is, instead of changing RTS/CTS from active to inactive after *every* packet header is received as in the preferred embodiment, the transition only occurs when there is a risk of overflow. The transmitter would continuously send

active.

7. go to 1)

The determination could be done as follows. The transmitter has a counter which maintains a count C of bits/bytes transmitted. The counter is reset to zero at the start of a packet. The transmitter continues to transmit until C = N'-1, then stops transmitting.

For an already started packet the RTS/CTS level change won't cause any effect (transmission is continued whatever happens as the receiver has indicated by a "flow on" level that it can receive the max. packet size).

In the preceding embodiments, there is a step of detecting when a predetermined portion (header of size n) of the next packet has been received is used to put RTS/CTS inactive. Although an example of a predetermined portion is given (header) this is not critical.

Whilst endeavouring in the foregoing specification to draw attention to those features of the invention believed to be of particular importance it should be understood that the Applicant claims protection in respect of any patentable feature or combination of features hereinbefore referred to and/or shown in the drawings whether or not particular emphasis is placed thereon.

receive a data packet; and

allowing transmission of a data packet from the transmitter to the receiver if there is enough available memory and preventing transmission of a data packet from the transmitter to the receiver if there is not enough available memory.

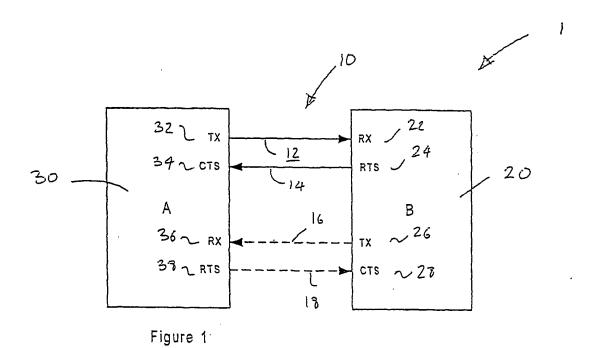
7. A receiver, for receiving packet data from a transmitter, comprising: an output for issuing flow control signals to the transmitter; an input for receiving data from the transmitter; a memory for storing data received from the transmitter; second detection means for detecting when a first portion of a packet has been received; and

flow control signal means for providing a flow control signal on the output in response to said second detection means.

- 8. A receiver as claimed in claim 7, wherein the flow control means provides a second flow control signal, stopping the transmitter from transmitting the next data packet, in response to the second detection means.
- 9. A receiver as claimed in claim 7 or 8, wherein the second flow control signal is provided independently of the availability of the memory and once per packet.
- 10. A receiver as claimed in any one of claims 7 to 9, additionally comprising

first detection means for detecting that the memory has enough space to store the next packet to be received, wherein the flow control signal means provides a first flow control signal, enabling transmission of the next packet, in dependence upon the first detection means.

11. A receiver as claimed in claim 10, wherein the first detection means detects for every packet that the memory has enough space to store the next packet to be received and the flow control signal means provides a first flow



Header user data

Figure 2:

INTERNATIONAL SEARCH REPORT

	INTERNATIONAL SEARCH REPORT		PCT/IB 02	2/00573
A CLASS	SIFICATION OF SUBJECT MATTER G06F13/38			
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According	to International Patent Classification (IPC) or to both national class	ification and IPC		
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IPC 7	documentation searched (classification system followed by classific $G06F$	cation symbols)		
Documenta	ation searched other than minimum documentation to the extent tha	at such documents are incl	uded in the fields s	earched
Electronic	data base consulted during the international search (name of data	hara and whom amplical		
	nternal, WPI Data, INSPEC	sase and, where practical	, search temps used)
C. DOCUM	IENTS CONSIDERED TO BE RELEVANT		<u> </u>	
Category *	Citation of document, with indication, where appropriate, of the	relevant passages		Relevant to claim No.
		· · ·		
4	EP 0 685 797 A-(HEWLETT PACKARD CO) 6 December 1995 (1995-12-06) column 2, line 10 - line 51 column 3, line 30 -column 4, line 17 abstract; claim 1		1-16	
Ą	EP 0 632 391 A (NAT SEMICONDUCTOR CORP) 4 January 1995 (1995-01-04) column 3, line 39 -column 4, line 4 abstract		1-16	
١	US 6 046 995 A (WESTERGAARD DAVID ET AL) 4 April 2000 (2000-04-04) column 2, line 41 -column 3, line 13		1–16	
4	EP 1 134 665 A (EXAR CORP) 19 September 2001 (2001-09-19) the whole document			1–16
	her documents are listed in the continuation of box C.	X Patent family n	nembers are listed i	n annex.
'A' document defining the general state of the art which is not considered to be of particular relevance 'E' earlier document but published on or after the International filing date 'L' document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified) 'O' document referring to an oral disclosure, use, exhibition or other means 'P' document published prior to the international filing date but		 To later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention "X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone "Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art. 		
etter tr	nan the priority date claimed actual completion of the international search	*&* document member of		
	November 2002	Date of mailing of the 18/11/20		rch report
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-	European Patent Office, P.B. 5818 Patentiaan 2 NL - 2280 HV Rijswijk Tel. (+31-70) 340-2040, Tx. 31 651 epo nl, Fax: (+31-70) 340-3016	Nguyen Xuan Hiep, C		